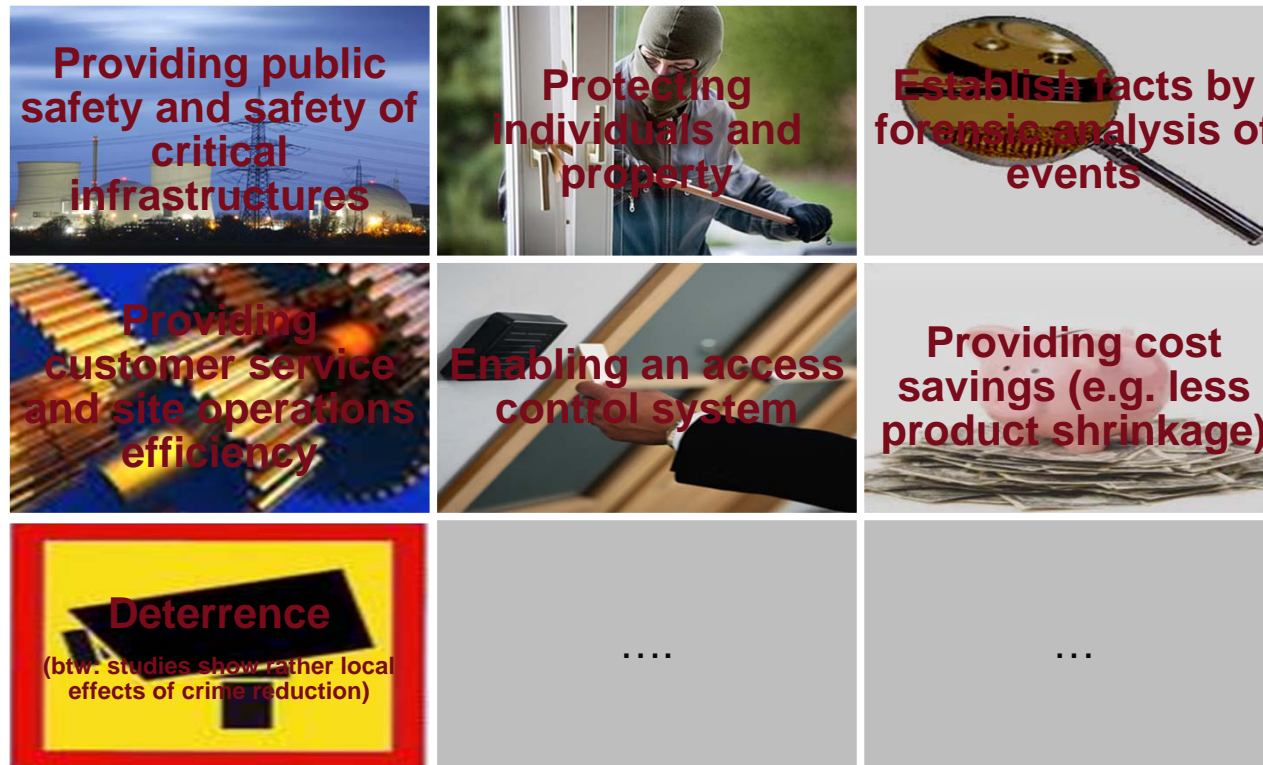


Next Generation Video Surveillance

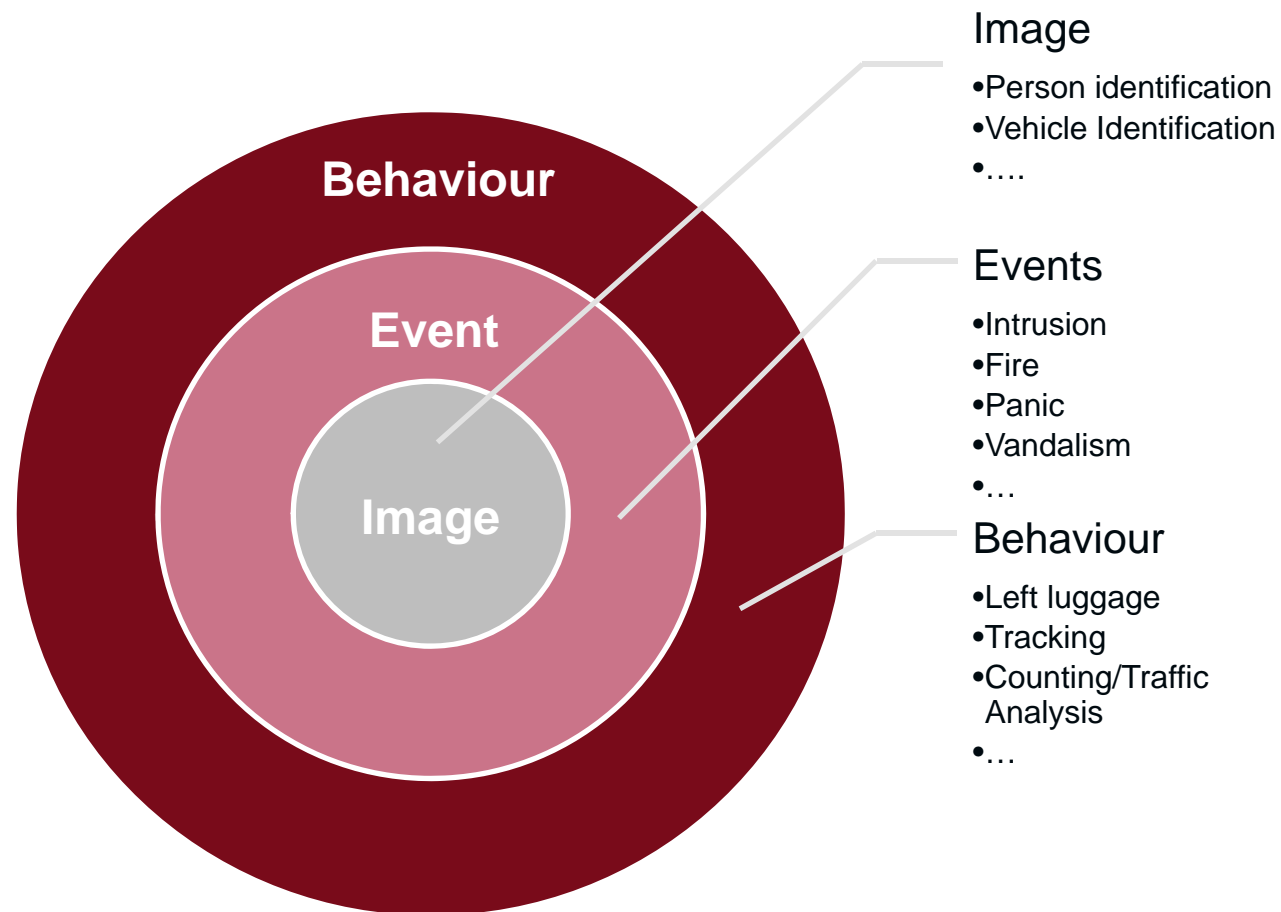
Innovations and solutions



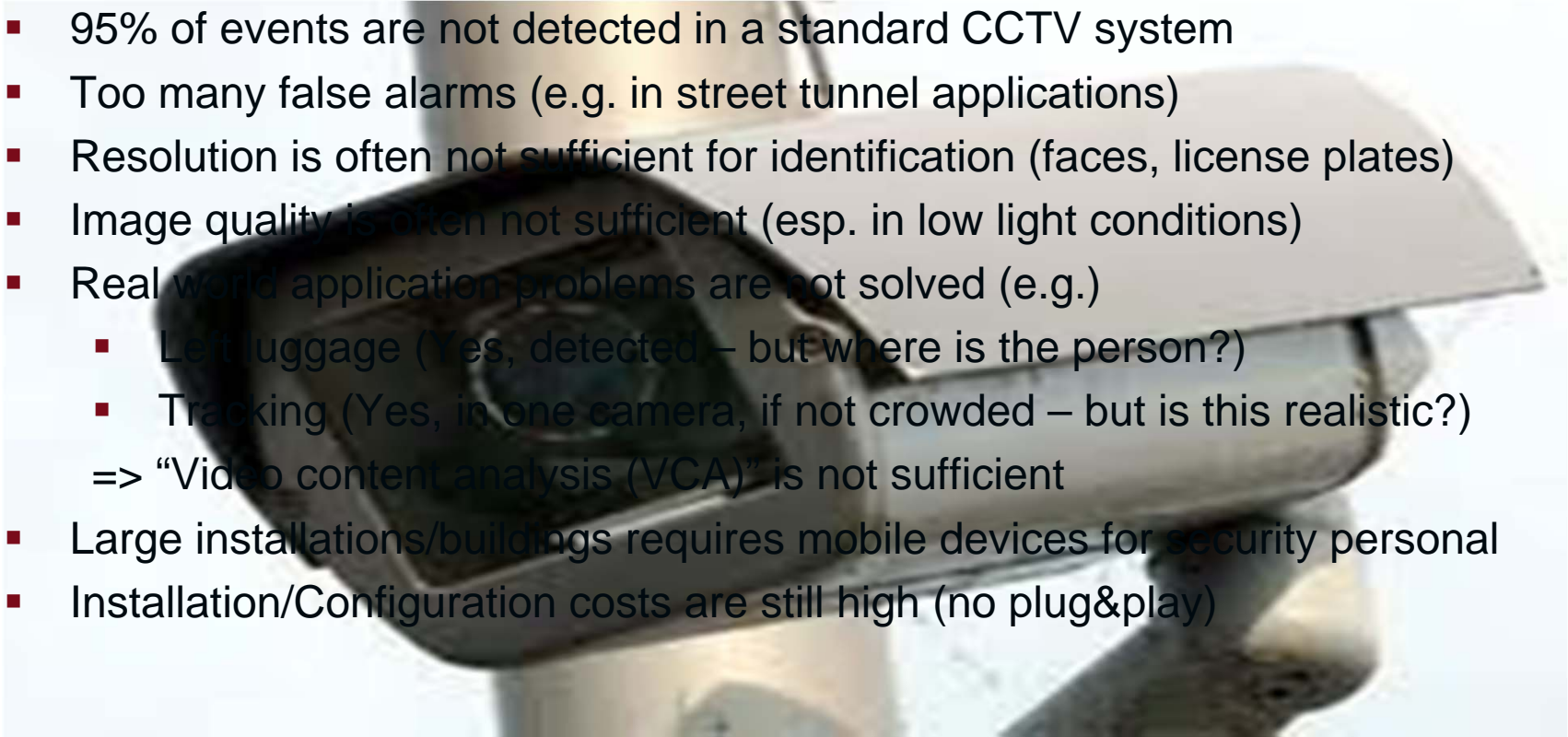
Reasons for video surveillance...



...pose different requirements on technical level

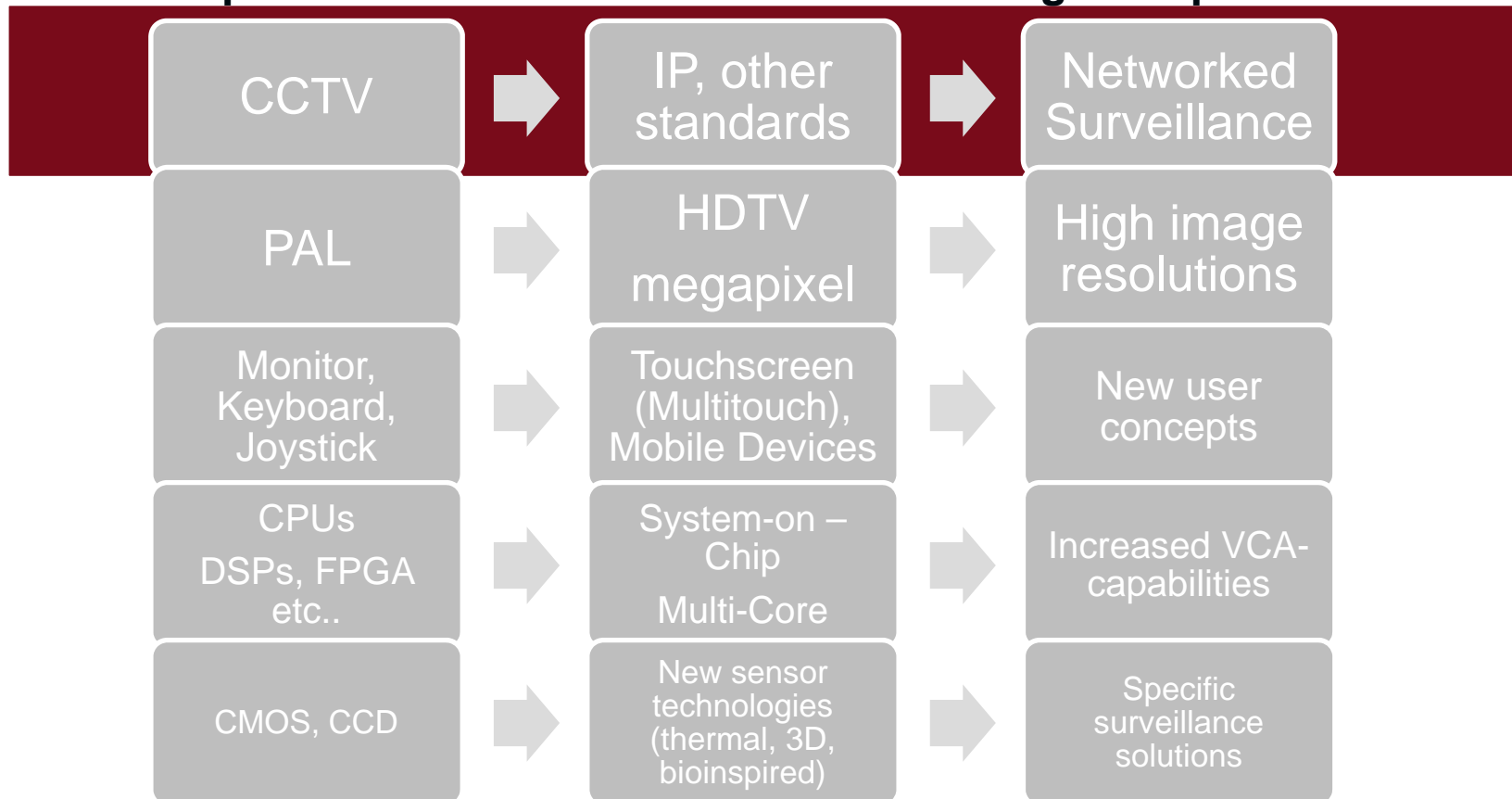


Motivation - Why today's surveillance systems may fail ?

- 
- 95% of events are not detected in a standard CCTV system
 - Too many false alarms (e.g. in street tunnel applications)
 - Resolution is often not sufficient for identification (faces, license plates)
 - Image quality is often not sufficient (esp. in low light conditions)
 - Real world application problems are not solved (e.g.)
 - Lost luggage (Yes, detected – but where is the person?)
 - Tracking (Yes, in one camera, if not crowded – but is this realistic?)
 - ⇒ “Video content analysis (VCA)” is not sufficient
 - Large installations/buildings requires mobile devices for security personal
 - Installation/Configuration costs are still high (no plug&play)

Main Statements

Disruptive Innovations lead to new technologies/capabilities



Transmission - Systembalancing

Where to do the storage/analytics ?

Camera/Encoder



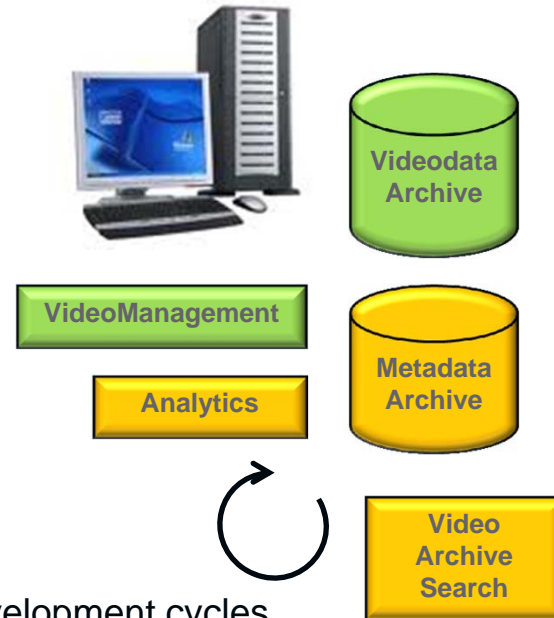
Analytics

Transmission

- proprietary
- standard
- only events
- metadata

PSIA, ONVIF

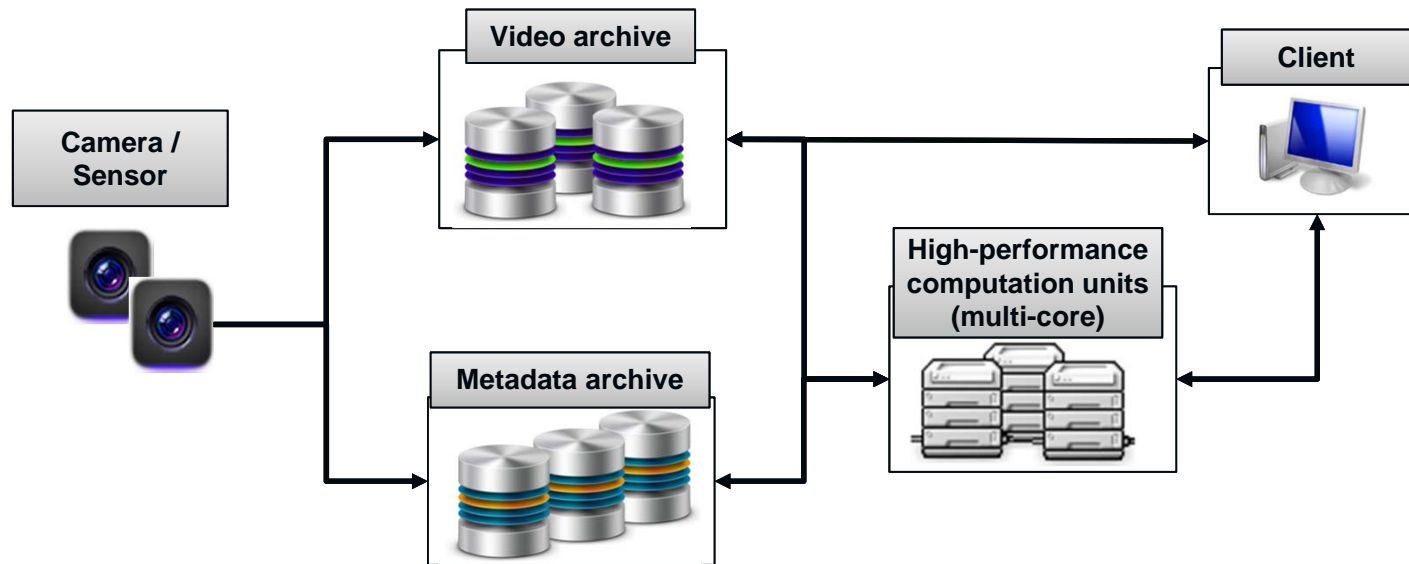
Client/Server



- difficult, slow (=> expensive) development
- limited performance
- + intelligent device: works standalone
- + cheap
- + embedded = reliable

- + faster development cycles
- + fast update cycles
- VCA on compressed data (no raw data available)
- single point of failure

Future M2M (Machine-2-Machine) Architecture

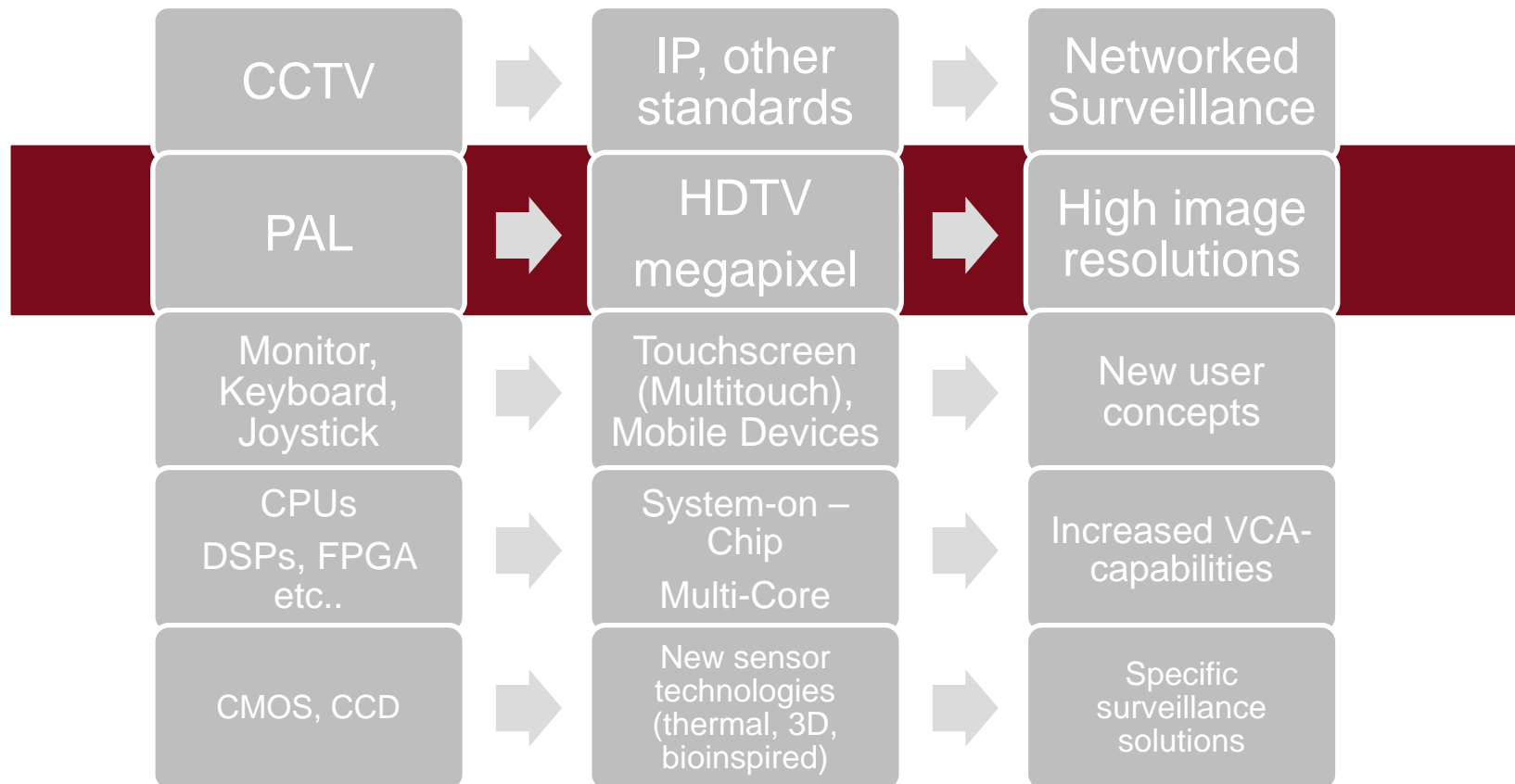


Future M2M Architecture – Ways2Go

- Standards !
 - IP – telephony, TV, distributed business solutions – Plug & Play
 - PSIA – ONVIF --- Only first step!
 - ONVIF has 800 conformant products (May, 11th; 2011)
- Open Networks - Cloud-Computing – Hosted Video - Hosted Services
 - IT-Security
 - IT-Reliability
 - Privacy
 - Legal and Social Issues

Main Statements

Disruptive Innovations lead to new technologies/capabilities



PAL => HDTV, Megapixel

	PAL	720p	1080p
Resolution	576 x 768	720 x 1.280	1.080 x 1.920
Pixels per image	442.368	921.600	2.073.600
Pixels per s	11.059.200	46.080.000	62.208.000
Frequency	50 Hz (interl.)	50 Hz (progr.)	60 Hz (progr.)
Format	4:3	16:9	16:9



High video resolution leads to data explosion

**Dataexplosion
Videodata**

1 Zetabyte (10^{21})
in 2010



**Intelligent interpretation
of pattern**

*From „data“ to
„information“ using
economical systems*

1000 and more videos
(live - and hours in the archive)



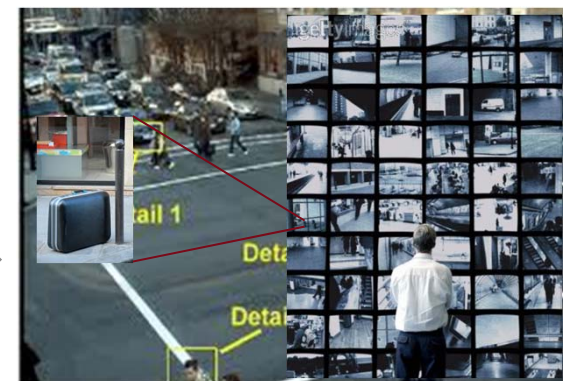
Large installation (1000 – 10.000) cameras

Operator miss 95% of the events after 20
min. due to information overflow

intelligent
interactive
Video
Content
Analysis



Who, What, Where, When, Why ?
Interactive Situation

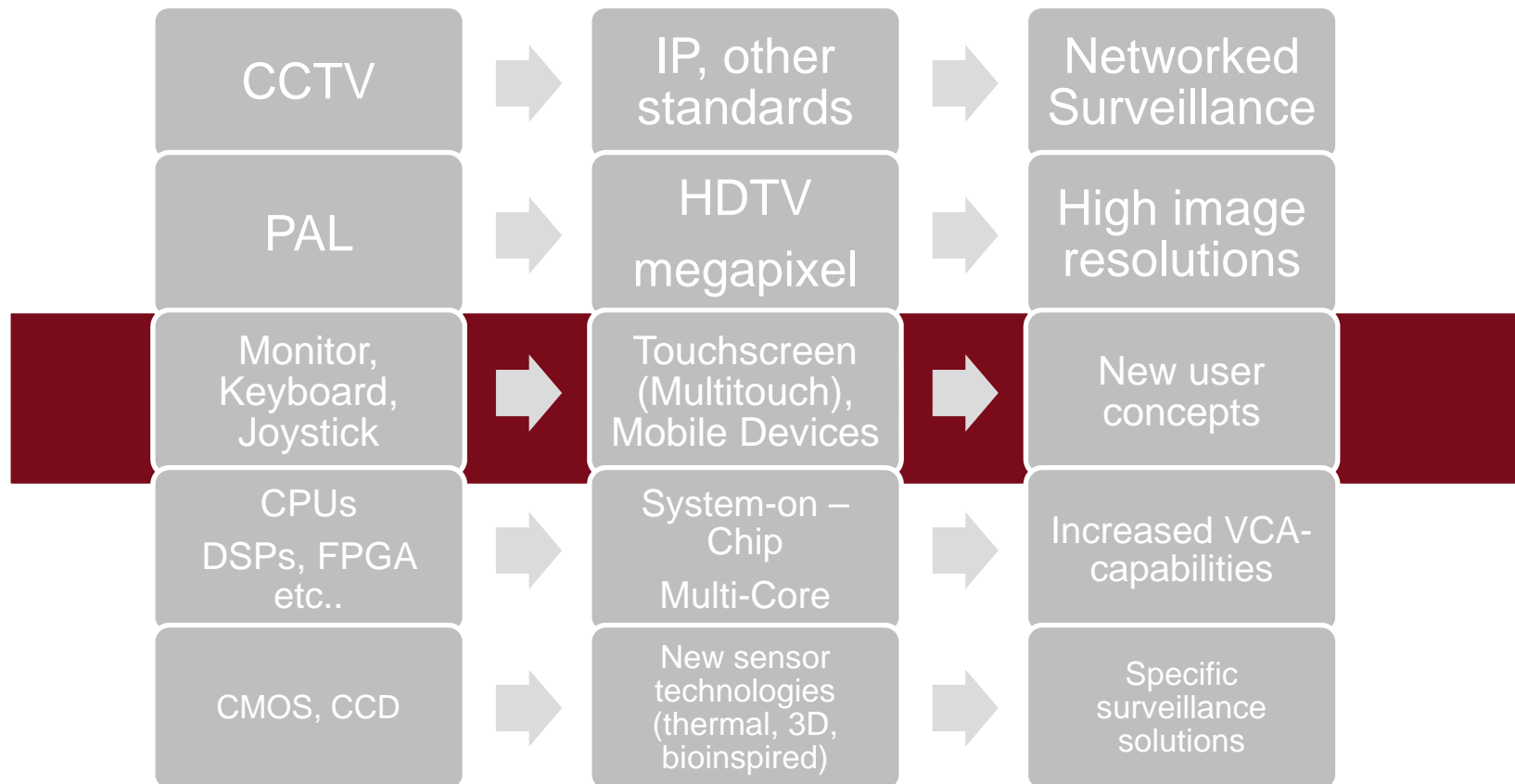


Q&A:

„Where is the person that left the luggage now?
Which person was close to the yellow car?“

Main Statements

Disruptive Innovations lead to new technologies/capabilities



New devices (mobile devices, tablets), New interfaces

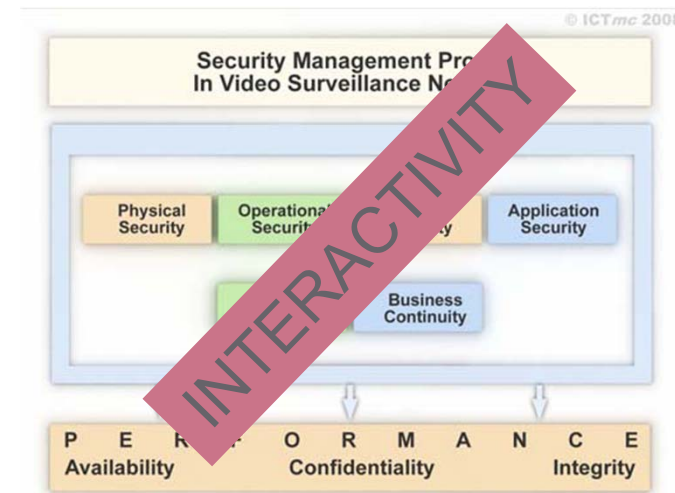
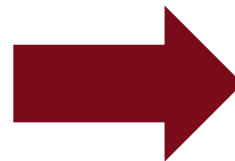
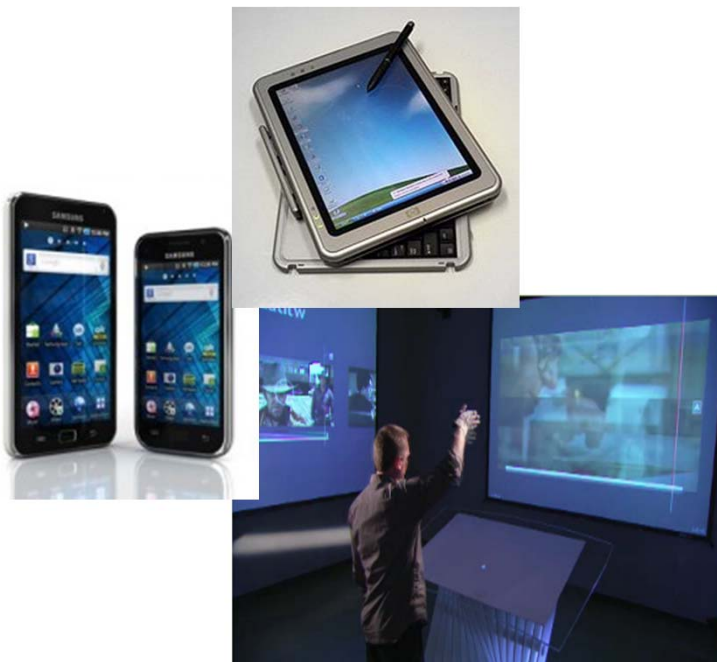


Touch, gesture;
language



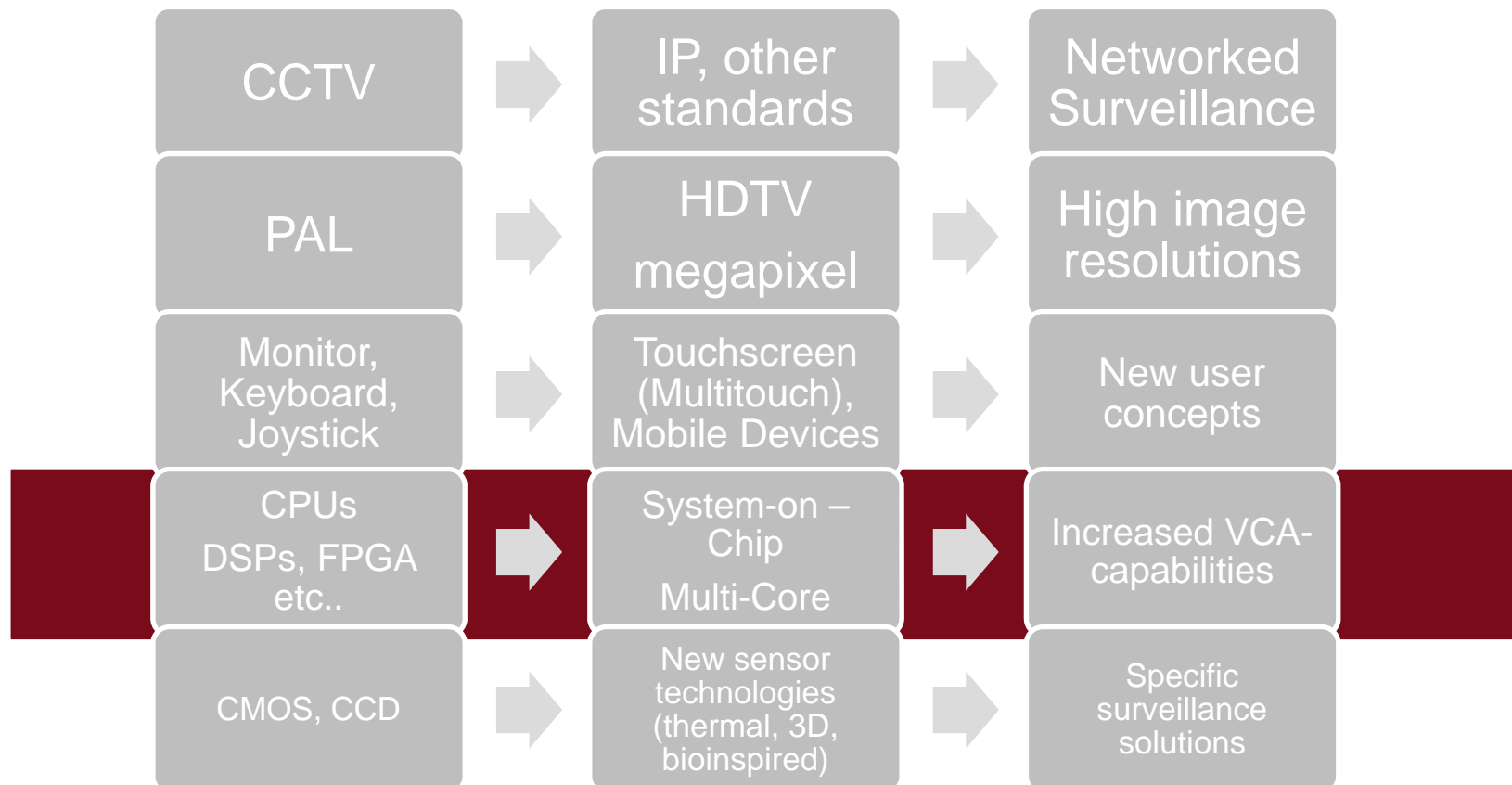
G-speak/Der Standard

...lead to new concepts/processes etc...

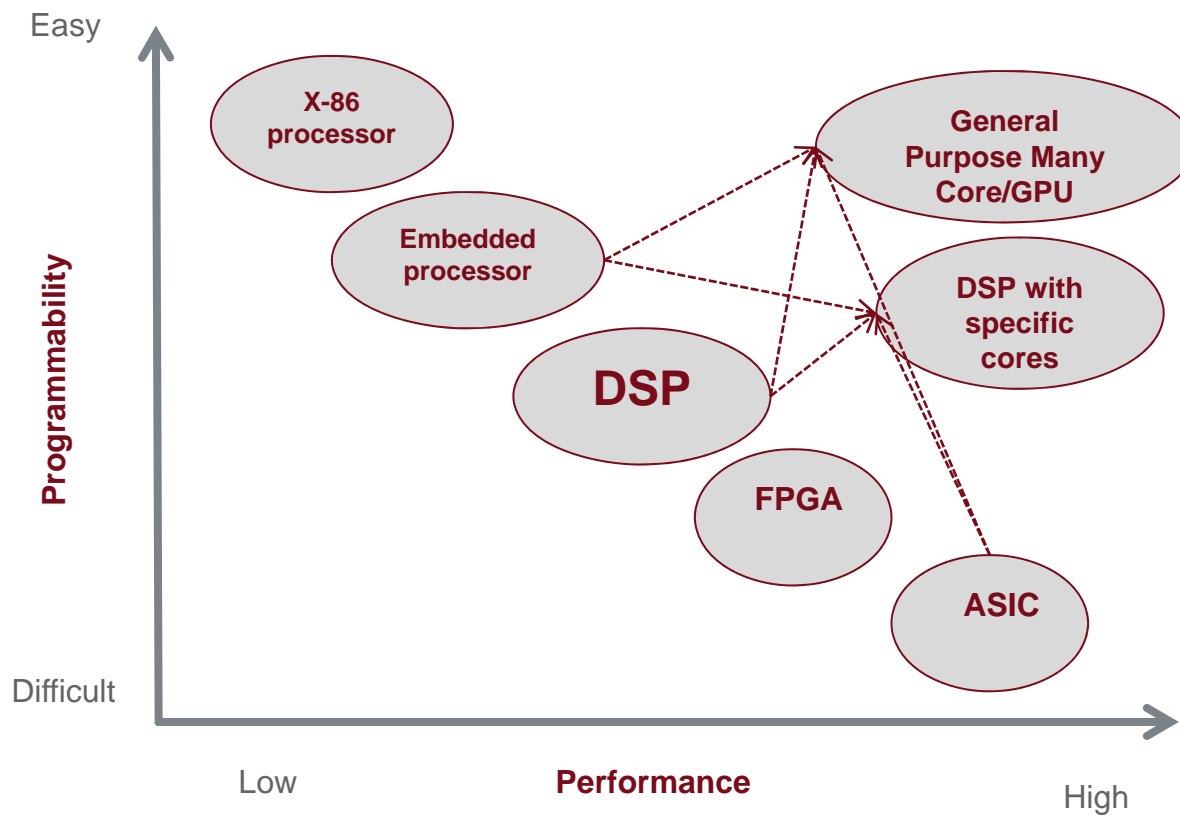


Main Statements

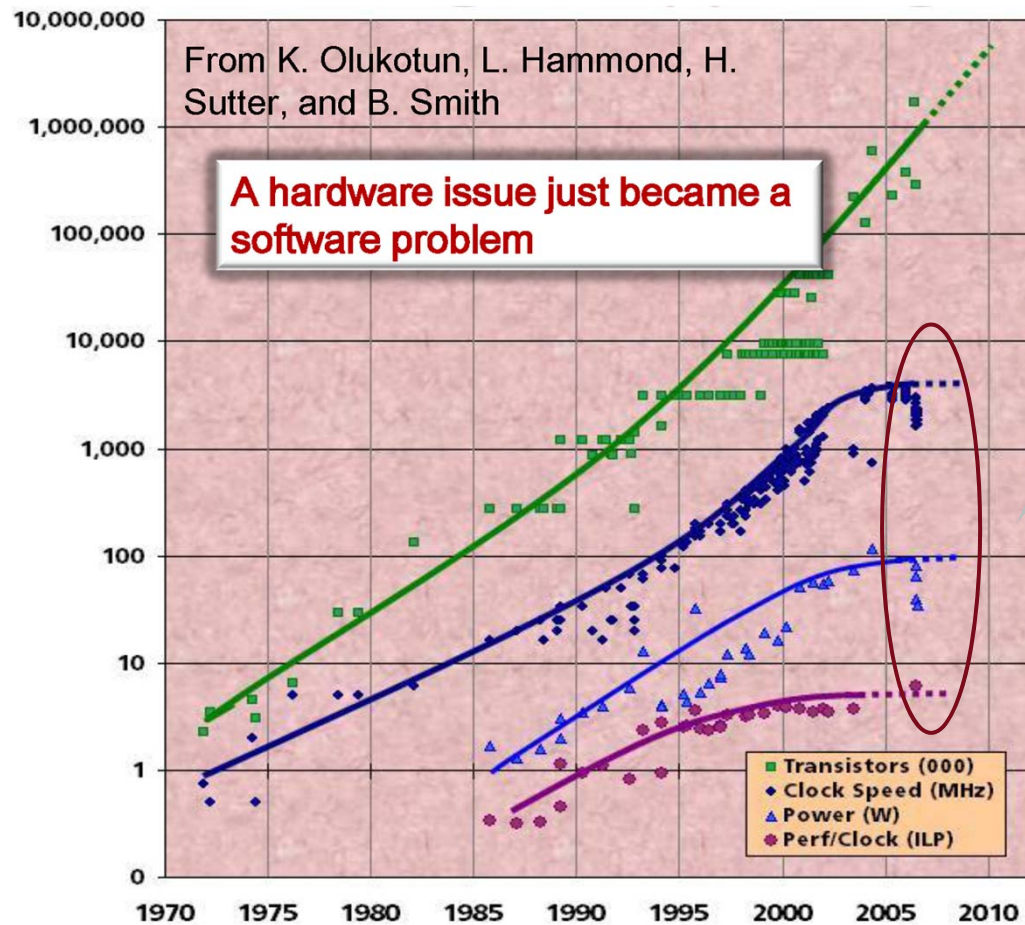
Disruptive Innovations lead to new technologies/capabilities



Processor Landscape



Processors - MultiCore Driving Forces - Technology



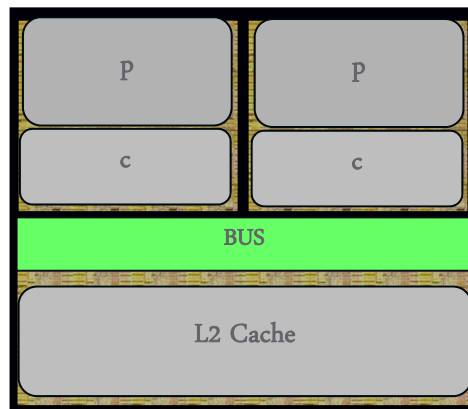
- **Power Wall**
 - $Power = C \times V^2 \times f$
 - $f \text{ prop. } V \rightarrow P \text{ prop. } V^3$
 - Reduce frequency and Voltage
- **ILP (Instruction Level Parallelism) Wall**
- **Memory Wall**

The only known way to overcome this dilemma is parallelism!

MultiCore Scaling Trends

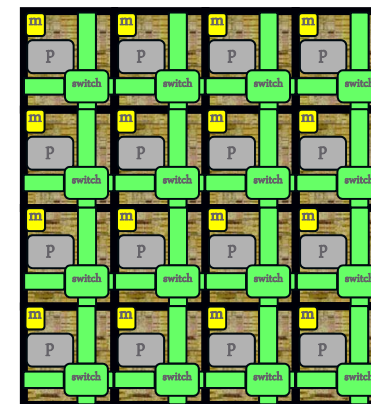
Today

- A few large cores on each chip
- Diminishing returns prevent cores from getting more complex
- Only option for future scaling is to add more cores
- Still some shared global structures: bus, L2 caches



Tomorrow

- 100's to 1000's of simpler cores [S. Borkar, Intel, 2007]
- Simple cores are more power and area efficient
- Global structures do not scale; all resources must be distributed



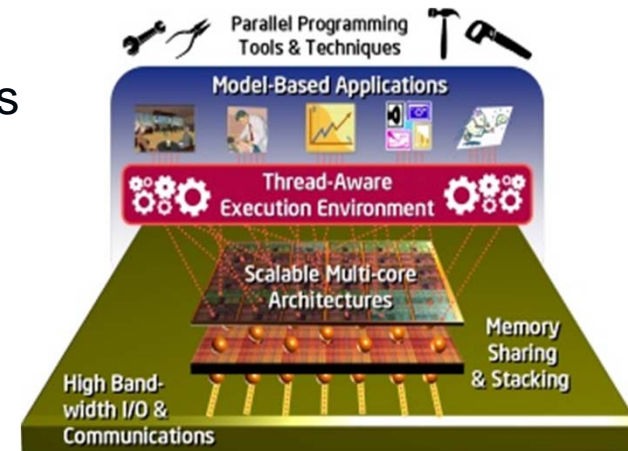
	2003	2005	2007	2009	2011	2013	2015	2017
Technology Node (nm)	90	65	45	32	22	16	11	8
Integration Capacity	2	4	8	16	32	64	128	256

MultiCore Challenges

MultiCore can close the “Moore’s Gap” - parallelism is the key for growing performance → a new business model, but ...

- Scalability
 - Architectures that grow easily with each new technology generation
 - How do we turn additional cores into additional performance?

- Programming
 - Traditional parallel programming techniques are hard
 - Parallel machines were rare and used only by rocket scientists
 - Multicores are ubiquitous and must be programmable by anyone



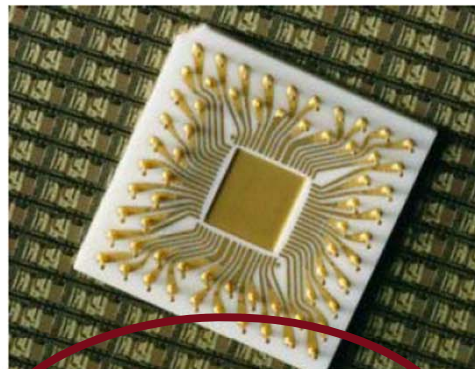
VCA - Factors that influence VCA

3 Key Variables that Influence Success



Environmental Factors

- Indoor/Outdoor
- Camera Angle
- Distance
- Lighting/WDR/etc
- Activity Level



Computational Factors

- Processing Power
- Real-time vs post-processing



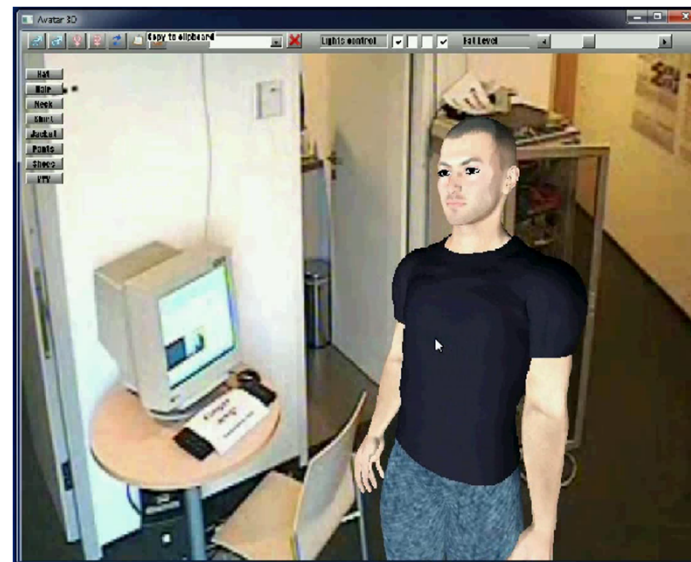
VMS Integration

- GUI
- Reporting
- Alerting

Ref.: Aimetis, J.Schorn (CEO)

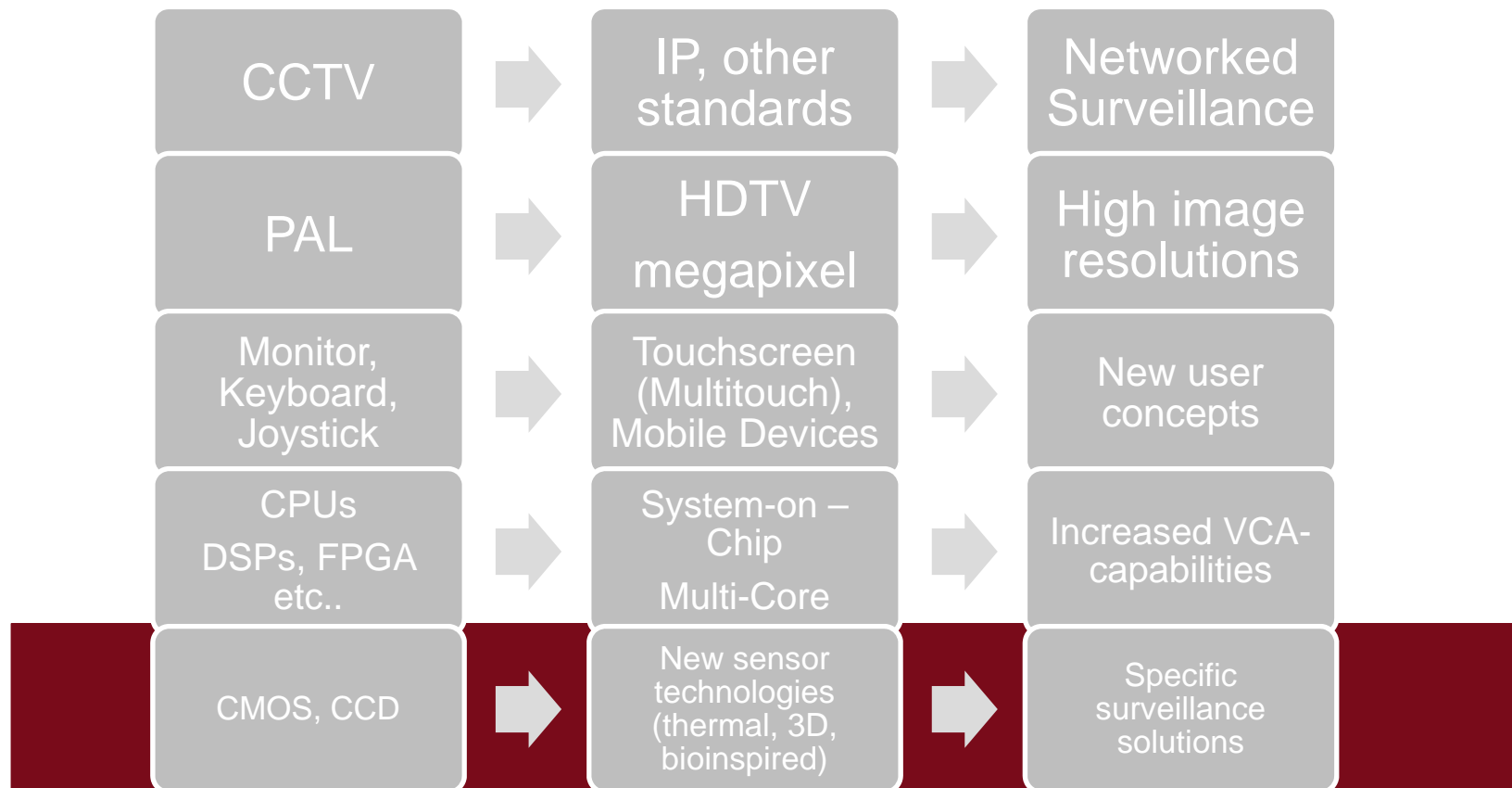
Advanced Video Content Analysis

- Appearance-based algorithms need processing power – Parallelism is possible
- Search and retrieval processes are naturally interactive
- Multi-camera approaches for full coverage



Main Statements

Disruptive Innovations lead to new technologies/capabilities



New (camera) sensor technologies

- CCD and CMOS show incremental improvements
- Radical changes can be seen for other sensors - examples
 - Thermal: uncooled sensors with **price drop** from sizes of 250k€ to 5k€
 - Stereo and Time-of-flight technology: **3D-vision**
 - Event-based sensors: **combination of low-light, high-speed and privacy**



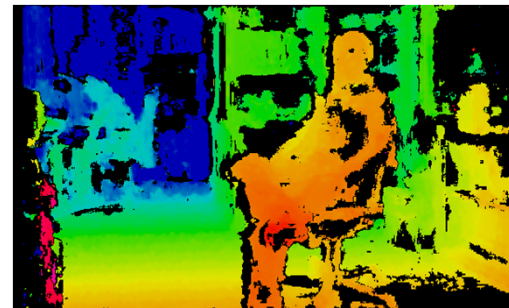
Thermal sensors

- Uncooled sensors dropped prices into reasonable level for broad application
- Main benefit: Increased „visibility“ especially in low-light conditions



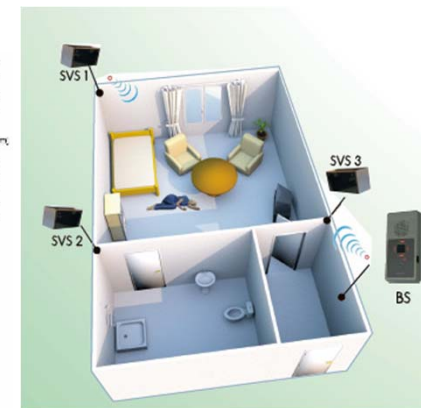
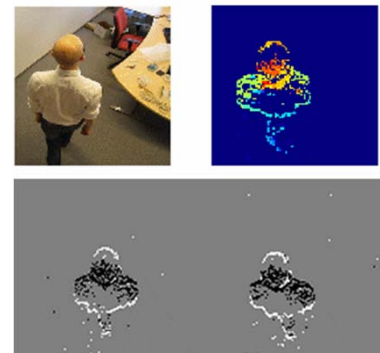
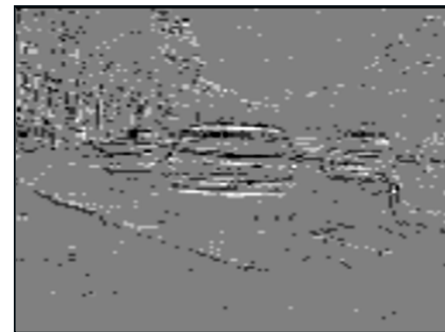
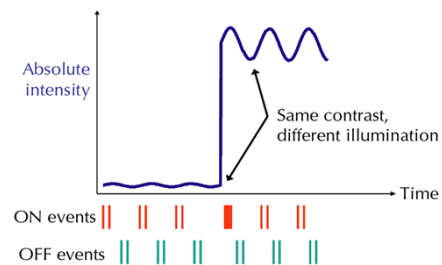
3D Vision – Stereo/Time-of-Flight

- Depth information – technically described as 2½ D
 - Two cameras with certain distance (base-line)
 - One Time-of-Flight camera using active illumination (PMD)
- Visual information is more reliable
 - Foreground/background segmentation
 - Shadows/Motion



Event-based sensors

- Event = change of light in a pixel is signalled
- Instantan (few μs) not frame-based
- In every pixel (locally independent – high sensitivity)
- No image details => Privacy-by-design



Main Statements

Disruptive Innovations lead to new technologies/capabilities

Summary – The Outlook

Disruptive Innovations lead to new technologies/capabilities
New technologies/capabilities lead to Next Generation Surveillance Systems



From	Videotransmission	to	Situation Awareness
From	watching	to	interaction
From	alarming	to	decision support
From	data overflow	to	information access
From	inflexible architecture	to	distributed services



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